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College of Natural Sciences  
Department of Mathematics  
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**Qualifying Examination**

Area: Computational Analysis

Date: 17 February 2012

Solve any three of the following five problems.

1. A matrix  $A$  is symmetric diagonally dominant (SDD) if:  
(i) for all  $i, j$   $A_{ij} = A_{ji}$ , (ii) for all  $i$ ,  $A_{ii} \geq \sum_{j \neq i} |A_{ij}|$ .
  - (a) (1 pt.) Give a  $3 \times 3$  SDD matrix.
  - (b) (2.5 pts.) State Jacobi's iteration for the matrix you gave above. Does it converge?
  - (c) (6.5 pts.) Does the Jacobi iteration converge for all SDD matrices? Prove your answer.

**Hint:** You may want to consider the spectral radius, and an upper bound to it computed through Gershgorin's theorem.

2. A matrix  $P$  is a projection matrix if  $P^2 = P$ . A matrix  $R$  is a reflection matrix if  $R^2 = I$ .
  - (a) (2 pts.) If  $P$  is a projection matrix, prove that  $I - P$  is also a projection matrix. Also prove that  $P(I - P) = 0$ .
  - (b) (2 pts.) If  $R$  is a reflection matrix, prove that  $(I - R)/2$  is a projection matrix.
  - (c) (3 pts.) What are the two possible eigenvalues of a projection matrix  $P$ ? What are the two possible eigenvalues of a reflection matrix  $R$ ? Prove your answer.  
**Hint:** Consider the eigenvalue decomposition of the two matrices.
  - (d) (3 pts.) Give a simple algorithm for solving linear systems  $Px = b$ , where  $P$  is a projection matrix. The algorithm should use only matrix-vector multiplications and vector comparisons. In your answer, ignore floating point errors. Justify the algorithm.

3. Consider solving the linear system  $Ax = b$ , where  $A$  is an  $n \times n$  and nonsingular matrix. Define the condition number of the matrix  $A$  as  $\text{cond}(A) = \|A\| \|A^{-1}\|$ , where  $\|\cdot\|$  is an induced matrix norm.

- (a) (3 pts.) Assume that  $x \in \mathbb{R}^n$  is the solution of the linear system where  $b \neq 0$  and  $\delta x \in \mathbb{R}^n$  satisfies

$$A(x + \delta x) = b + \delta b$$

for  $\delta b \in \mathbb{R}^n$ . Find upper and lower bounds for

$$\frac{\|\delta x\|}{\|x\|} \div \frac{\|\delta b\|}{\|b\|}$$

in terms of the  $\text{cond}(A)$ .

- (b) (2.5 pts.) Show that  $\text{cond}(A)_* \leq \text{cond}(A)$ , where  $\text{cond}(A)_* = \max_i |\lambda_i| / \min_i |\lambda_i|$  and  $\lambda_i$  is eigenvalue of  $A$ .
- (c) (2.5 pts.) Show that  $\text{cond}(A) \geq 1$  and provide an example where  $\text{cond}(A)_* = 1$  but  $\text{cond}(A)_\infty$  can be made arbitrary large, where  $\text{cond}(A)_\infty$  is the condition number of  $A$  in the maximum norm  $\|\cdot\|_\infty$ .
- (d) (2 pts.) Assume that the matrix  $A$  can be written as  $A = UDV^T$ , where  $U$  and  $V$  are orthogonal matrices,  $D = \text{diag}(d_1, d_2, \dots, d_n)$ , and  $d_1 \geq d_2 \geq \dots \geq d_n > 0$ . Compute  $\text{cond}(A)_2$  in terms of the quantities  $d_i$ , where  $\text{cond}(A)_2$  is the condition number of  $A$  in the 2-norm.
4. A function  $f(x) \in C^{m+1}([a, b])$  has a root  $\alpha \in [a, b]$  of multiplicity  $m > 1$  if there is a function  $h \in C^{m+1}([a, b])$  such that  $h(\alpha) \neq 0$  and

$$f(x) = (x - \alpha)^m h(x). \quad (1)$$

- (a) (3 pts.) Show that if  $f(x)$  has a root  $\alpha$  of multiplicity  $m$ , then the Newton's method converges linearly to  $\alpha$  with rate of convergence  $(m - 1)/m$ .
- (b) (3 pts.) Prove that for a function  $f(x)$  with a root  $\alpha$  of multiplicity  $m$  the modified Newton's method

$$x_{i+1} = x_i - m \frac{f(x_i)}{f'(x_i)}$$

converges locally and quadratically to  $\alpha$ .

- (c) Apply the Newton's method and the modified Newton's method to find the root of the following function

$$f(x) = x^m, \quad m > 1.$$

- (i) (2 pts.) Estimate the error of each method.
- (ii) (2 pts.) Find the value of  $m$  that makes the Newton's method to converge slower than the bisection method.

5. Consider the initial value problem

$$y'(x) = f(x, y(x)), \quad a \leq x \leq b, \quad y(a) = y_0, \quad (2)$$

and the linear multi-step method to approximate its solution

$$y_{n+k} = \alpha_{k-1}y_{n+k-1} + \alpha_{k-2}y_{n+k-2} + \dots + \alpha_0y_n + h[\beta_k f(x_{n+k}, y_{n+k}) + \beta_{k-1}f(x_{n+k-1}, y_{n+k-1}) + \dots + \beta_0f(x_n, y_n)], \quad (3)$$

where the starting points  $y_0, y_1, \dots, y_{k-1}$  are given.

- (a) (4.5 pts.) Find conditions on the  $\alpha$ 's and  $\beta$ 's in (3) that lead to an implicit linear one-step method which is stable and at least of order two.
- (b) (2.5 pts.) This is an implicit method and to approximate  $y_{k+1}$  (when it is needed to evaluate  $f(x_{k+1}, y_{k+1})$ ), in each iteration, let's consider an explicit method as a predictor. Write down the resultant methods if we approximate  $y_{k+1}$ , in each iteration, by using the Euler's method.
- (c) (3 pts.) Show that the resultant method in (b) is at least of order two.